



ЗАО "СЕРВОТЕХНИКА-НЕВА"  
196066, Санкт-Петербург,  
Московский пр. 212 офис 3061  
Тел./Факс: (812)380-15-31  
E-mail: info@servotech.spb.ru  
Web: www.servotech.spb.ru

# COMBIVERT



**Installationsanleitung**  
**Installation Guideline**

**B-Gehäuse**  
**B-Housing**

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Diese Anleitung beschreibt den KEB COMBIVERT F5-Servo. Im Einzelnen wird auf den Einbau, die Anschlussmöglichkeiten sowie die grundlegende Bedienung eingegangen. Aufgrund der vielfältigen Einsatz- und Programmiermöglichkeiten ist der anwendungsspezifische Anschluss- bzw. Verdrahtungsplan, die Parametereinstellung sowie Hinweise zur Inbetriebnahme der Dokumentation des Maschinenherstellers zu entnehmen. Eine Aufstellung von Anleitungen und Dokumenten zur Unterstützung für Konstruktion, Dokumentation und Service sind am Ende dieser Anleitung zusammengefasst. Die verwendeten Piktogramme entsprechen folgender Bedeutung:



Gefahr  
Warnung  
Vorsicht



Achtung,  
unbedingt  
beachten



Information  
Hilfe  
Tip

This manual describes the KEB COMBIVERT F5. Particular attention is paid to the installation, the connection as well as the basic operation. Due to the various application and programming possibilities, the application-specific connection and/or wiring diagram, the parameter adjustment as well as instructions to the start-up are to be taken from the documentation of the machine manufacturer.

A list of instruction manuals and documents giving assistance for the construction, documentation and service is provided at the end of this manual. The used pictograms have following significance:



Danger  
Warning  
Caution



Attention,  
observe at  
all costs



Information  
Aide  
Tip

<b>1.</b>	<b>Safety and Operating Instructions .....</b>	<b>30</b>
<b>2.</b>	<b>Product Description .....</b>	<b>31</b>
2.1	Application .....	31
2.2	Rating plate .....	31
2.3	Technical Data .....	32
2.3.1	230 V-class .....	32
2.3.2	400 V-class .....	33
2.4	Dimensions and Terminals .....	34
<b>3.</b>	<b>Installation and Connection .....</b>	<b>35</b>
3.1	Control Cabinet Installation .....	35
3.2	EMC-conform Installation .....	35
3.3	Connection of Power Circuit .....	36
3.3.1	Terminalstrip X1A .....	36
3.3.2	Wiring instructions .....	36
3.3.3	Mains connection .....	37
3.3.4	Motor connection .....	38
3.3.5	External temperature monitoring .....	38
3.3.6	Connection of the braking resistor with temperature monitoring .....	39
3.4	Control Board Basic .....	40
3.4.1	X2A Control Terminal Strip .....	40
3.4.2	Connection of the control terminal strip .....	41
3.5	Control Board General .....	42
3.5.1	X2A Control Terminal Strip .....	42
3.5.2	Connection of the control terminal strip .....	43
<b>4</b>	<b>Operation of the Unit .....</b>	<b>44</b>
4.1	Operation Accessories .....	44
4.1.1	With HSP5 cable and without operator .....	44
4.1.2	Digital operator (Part no.: 00.F5.060-1000) .....	44
4.1.3	Interface operator (Part No.: 00.F5.060-2000) .....	44
4.1.4	Remote control (HSP5-extension) .....	45
4.1.5	Other operators .....	45
4.2	Keyboard Operation .....	45
4.2.1	Parameter numbers and values .....	45
4.2.2	Resetting error messages .....	46
4.2.3	Password input .....	46
<b>5.</b>	<b>Parameter description .....</b>	<b>47</b>
<b>6.</b>	<b>Certifications .....</b>	<b>53</b>
6.1	CE-Marking .....	53
6.2	Manufacturer's Declaration .....	53
6.3	UL / CUL - Marking .....	53
<b>7.</b>	<b>Additional Manuals .....</b>	<b>54</b>

## 1. Safety and Operating Instructions



### Safety and operating instructions for drive converters

(in conformity with the low-voltage directive 73/23/EEC)

#### 1. General

In operation, drive converters, depending on their degree of protection, may have live, uninsulated, and possibly also moving or rotating parts, as well as hot surfaces.

In case of inadmissible removal of the required covers, of improper use, wrong installation or maloperation, there is the danger of serious personal injury and damage to property.

For further information, see documentation.

All operations serving transport, installation and commissioning as well as maintenance are to be carried out by skilled technical personnel (Observe IEC 364 or CENELEC HD 384 or DIN VDE 0100 and IEC 664 or DIN/VDE 0110 and national accident prevention rules!).

For the purposes of these basic safety instructions, „skilled technical personnel“ means persons who are familiar with the installation, mounting, commissioning and operation of the product and have the qualifications needed for the performance of their functions.

#### 2. Intended use

Drive converters are components designed for inclusion in electrical installations or machinery.

In case of installation in machinery, commissioning of the drive converter (i.e. the starting of normal operation) is prohibited until the machinery has been proved to conform to the provisions of the directive 89/392/EEC (Machinery Safety Directive - MSD). Account is to be taken of EN 60204.

Commissioning (i.e. the starting of normal operation) is admissible only where conformity with the EMC directive (89/336/EEC) has been established. The drive converters meet the requirements of the low-voltage directive 73/23/EEC. They are subject to the harmonized standards of the series DIN EN 50178/VDE 0160 in conjunction with EN 60439-1/ VDE 0660, part 500, and EN 60146/ VDE 0558.

The technical data as well as information concerning the supply conditions shall be taken from the rating plate and from the documentation and shall be strictly observed.

#### 3. Transport, storage

The instructions for transport, storage and proper use shall be complied with.

The climatic conditions shall be in conformity with EN 50178.

#### 4. Installation

The installation and cooling of the appliances shall be in accordance with the specifications in the pertinent documentation.

The drive converters shall be protected against excessive strains. In particular, no components must be bent or isolating distances altered in the course of transportation or handling. No contact shall be made with electronic components and contacts.

Drive converters contain electrostatic sensitive components which are liable to damage through improper use. Electric components must not be mechanically damaged or destroyed (potential health risks).

#### 5. Electrical connection

When working on live drive converters, the applicable national accident prevention rules (e.g. VBG 4) must be complied with.

The electrical installation shall be carried out in accordance with the relevant requirements (e.g. cross-sectional areas of conductors, fusing, PE connection). For further information, see documentation.

Instructions for the installation in accordance with EMC requirements, like screening, earthing, location of filters and wiring, are contained in the drive converter documentation. They must always be complied with, also for drive converters bearing a CE marking. Observance of the limit values required by EMC law is the responsibility of the manufacturer of the installation or machine.

#### 6. Operation

Installations which include drive converters shall be equipped with additional control and protective devices in accordance with the relevant applicable safety requirements, e.g. Act respecting technical equipment, accident prevention rules etc. Changes to the drive converters by means of the operating software are admissible.

After disconnection of the drive converter from the voltage supply, live appliance parts and power terminals must not be touched immediately because of possibly energized capacitors. In this respect, the corresponding signs and markings on the drive converter must be respected.

During operation, all covers and doors shall be kept closed.

#### 7. Maintenance and servicing

The manufacturer's documentation shall be followed.

**KEEP SAFETY INSTRUCTIONS IN A SAFE PLACE!**

## 2. Product Description

### 2.1 Application

The frequency inverter KEB COMBIVERT F5 serves exclusively for the control and regulation of asynchronous motors. The operation of other electric consumers is prohibited and can lead to the destruction of the unit.

Frequency inverters are components which are intended for the installation in electric systems or machines.

### 2.2 Rating plate

**10.F5.G1B-3A00**

#### Cooling

0: Standard  
1: Flat rear

A: Standard, varnished  
B: Flat rear, varnished

#### Interface type

0: none

#### Switching frequency / overload characteristic

5: 4 kHz/150%/180%  
A: 8 kHz/180%/216%

9: 4 kHz/180%/216%  
B: 16kHz/180%/216%

#### Input identification

0: 1ph 230 V AC/DC  
1: 3ph 230 V AC/DC  
6: 1ph 230 V AC

2: 1/3ph 230 V AC, or DC-Supply  
3: 3ph 400 V AC or DC-Supply

#### Housing type B

#### Accessory

1: GTR 7  
3: GTR 7 and integrated filter  
5: GTR 7 and integrated PFC

B: such as 1 but with driver relay  
D: such as 3 but with driver relay  
F: such as 5 but with driver relay

#### Control type

B: BASIC  
G: GENERAL

#### Series F5

#### Inverter size

## Product Description

### 2.3 Technical Data

#### 2.3.1 230 V-class

Inverter Size	05		07		09		10	
Housing size	B		B		B		B	
Phases	1	3	1	3	1	3	1	3
Output rated power [kVA]	0,9		1,6		2,8		4	
Max. rated motor power [kW]	0,37		0,75		1,5		2,2	
Output rated current [A]	2,3		4		7		10	
Max. short time current [A]	4,1		7,2		12,6		18	
OC-tripping current [A]	5		8,6		15,1		21,6	
Input rated current [A]	4,6	3,2	8	5,6	14	9,8	20	14
Input rated current (with PFC) [A]	3,7	-	6,4	-	-	-	-	-
Input active power (with PFC) [kW]	0,85	-	1,5	-	-	-	-	-
Max. permissible mains fuse (inert) [A]	16		20	16	20	16	25	20
Rated switching frequency [kHz]	16		16		16		8	
Max. switching frequency [kHz]	16		16		16		16	
Power loss at rated operation [W]	50		65		90		105	
Power loss with PFC [W]	85	-	130	-	-	-	-	-
Min. braking resistor [Ohm]	56		56		47		33	
Typ. braking resistor [Ohm]	180		180		100		68	
Max. braking current [A]	7,5		7,5		9,5		12	
Mains voltage U <sub>N</sub> [V]	180...260 ±0							
Mains frequency [Hz]	50 / 60 ±2							
Input rated voltage [V]	230							
Output voltage [V]	3 x 0...U <sub>N</sub>							
Output frequency [Hz]	0...400							
Min. motor line cross section [mm <sup>2</sup> ]	1,5		2,5	1,5	2,5	1,5	4	2,5
Max. motor line length (shielded) 4 kHz [m]	30		100		100		100	
Max. motor line length (shielded) 8 kHz [m]	20		50		100		100	
Max. motor line length (shielded) 16 kHz [m]	10		20		40		100	

## 2.3.2 400 V-class

<b>Inverter Size</b>	<b>05</b>	<b>07</b>	<b>09</b>	<b>10</b>	<b>12</b>
<b>Housing size</b>	<b>B</b>	<b>B</b>	<b>B</b>	<b>B</b>	<b>B</b>
Phases	3	3	3	3	3
Output rated power [kVA]	0,9	1,8	2,8	4	6,6
Max. rated motor power [kW]	0,37	0,75	1,5	2,2	4
Output rated current [A]	1,3	2,6	4,1	5,8	9,5
Max. short time current [A]	2,3	4,7	7,4	10,4	17
OC-tripping current [A]	2,8	5,6	8,9	12,5	21
Input rated current [A]	1,8	3,6	6	8	13
Max. permissible mains fuse (inert) [A]	16	16	16	16	20
Rated switching frequency [kHz]	16	16	8	8	4
Max. switching frequency [kHz]	16	16	16	16	4
Power loss at rated operation [W]	60	90	80	120	150
Min. braking resistor [Ohm]	390	120	120	82	82
Typ. braking resistor [Ohm]	620	620	390	270	150
Max. braking current [A]	2,2	7,5	7,5	10	10
Mains voltage $U_N$ [V]	305...500 $\pm 0$				
Mains frequency [Hz]	50 / 60 $\pm 2$				
Input rated voltage [V]	400 <sup>1)</sup>				
Output voltage [V]	3 x 0... $U_N$				
Output frequency [Hz]	0...400				
Min. motor line cross section [mm <sup>2</sup> ]	1,5	1,5	1,5	1,5	2,5
Max. motor line length (shielded) 4 kHz [m]	10	10	100	100	50
Max. motor line length (shielded) 8 kHz [m]	8	8	30	50	-
Max. motor line length (shielded) 16 kHz [m]	4	5	10	10	-

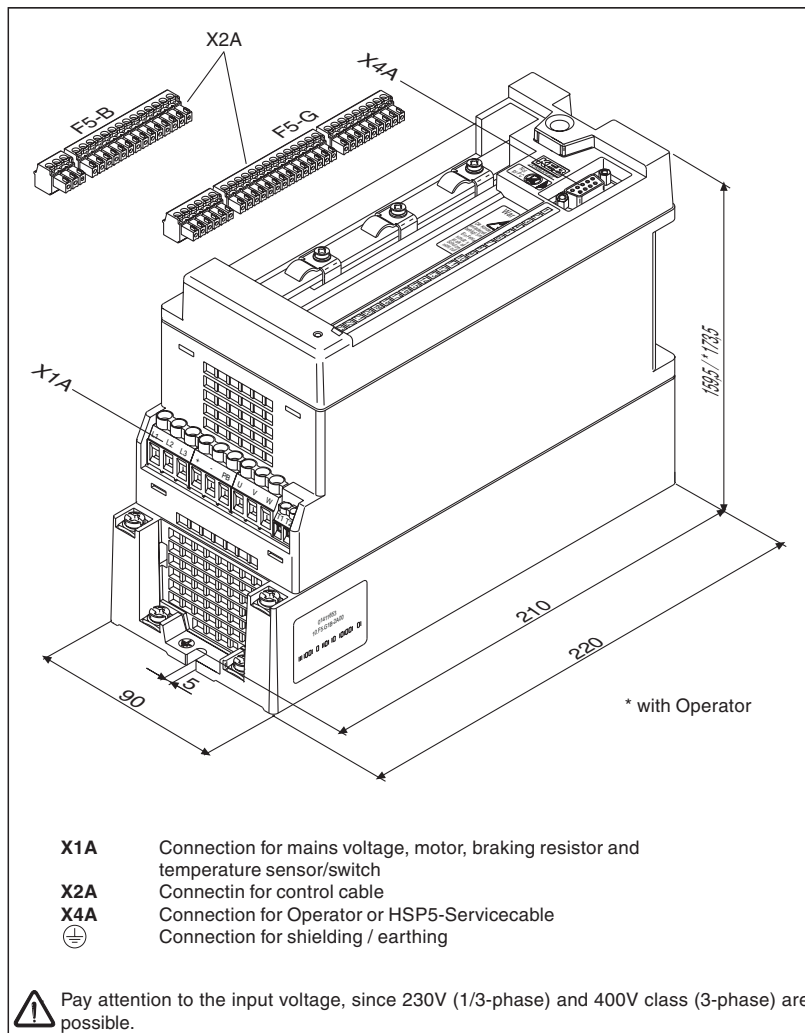
<sup>1)</sup> at mains voltage  $\geq 460$  V multiply the nominal current with factor 0.86



Site altitude max. 2000m. With site altitudes over 1000m a power reduction of 1% per 100m must be taken into consideration.

# Product Description

## 2.4 Dimensions and Terminals





## 3. Installation and Connection

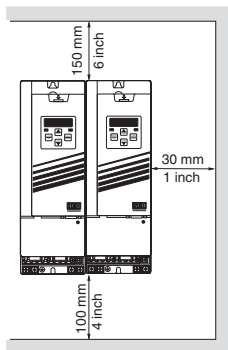
### 3.1 Control Cabinet Installation

Installation position and min. distances

Protective system:	IP20
Operation temperature:	-10...45 °C (-14...113 °F)
Storage temperature:	-25...70 °C (-13...158 °F)
max. heat sink temperature:	90 °C (194 °F)
Climatic category (EN 50178):	3K3
Relative humidity (without condensation):	max. 95 %



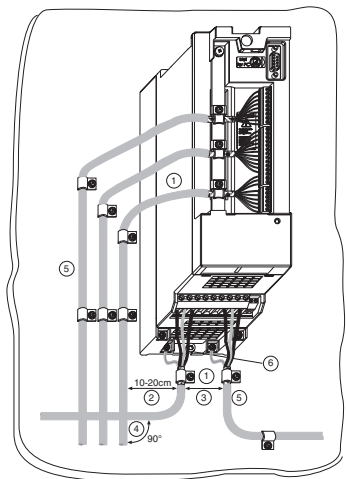
Protect the COMBIVERT against aggressive gases and aerosols !



### 3.2 EMC-conform Installation

- 1) Always apply the shielding of motor and control cables over a large contact surface on both sides.
- 2) Distance between control and power cables at least 10..20 cm (4...8 inch).
- 3) Lay motor and power cable separately.
- 4) If it cannot be avoided, cross control and power cables in a right angle.
- 5) Install all cables as close as possible to the mounting plate - ideal in a metal cable duct.
- 6) Mount COMBIVERT well conducting with the mounting plate. Remove the paint beforehand.

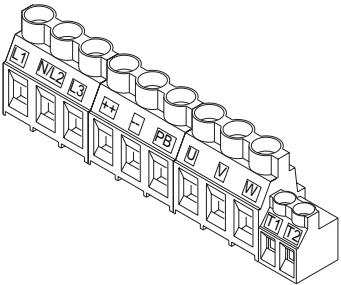
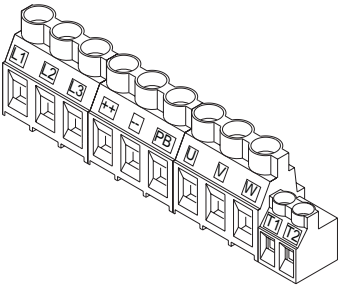
You can find further instructions regarding the EMC-conform wiring in the Internet at [KEB](http://KEB.com).



# Installation and Connection

## 3.3 Connection of Power Circuit

### 3.3.1 Terminalstrip X1A

	
<p>Terminal strip X1A / 230 V - class suitable for</p> <ul style="list-style-type: none"><li>• 180...260 V AC / 1-phase (L1/N)</li><li>• 180...260 V AC / 3-phase (L1, L2, L3)</li><li>• DC-Supply 250...370 V DC (++, --)</li></ul>	<p>Terminal strip X1A / 400 V - Class suitable for</p> <ul style="list-style-type: none"><li>• 305...500 V AC / 3-phase (L1, L2, L3)</li><li>• DC-Supply 420...720 V DC (++, --)</li></ul>
<ul style="list-style-type: none"><li>• ++, PB</li><li>• U, V, W</li><li>• T1, T2</li></ul>	<p>Braking resistor Motor Temperature sensor / switch (see chapter 3.3.6)</p>

### 3.3.2 Wiring instructions



*Absolutely observe the connecting voltage of the KEB COMBIVERT. A 230V-unit will be immediately destructed on a 400V-power supply.*



*Never exchange the mains and motor cables.*



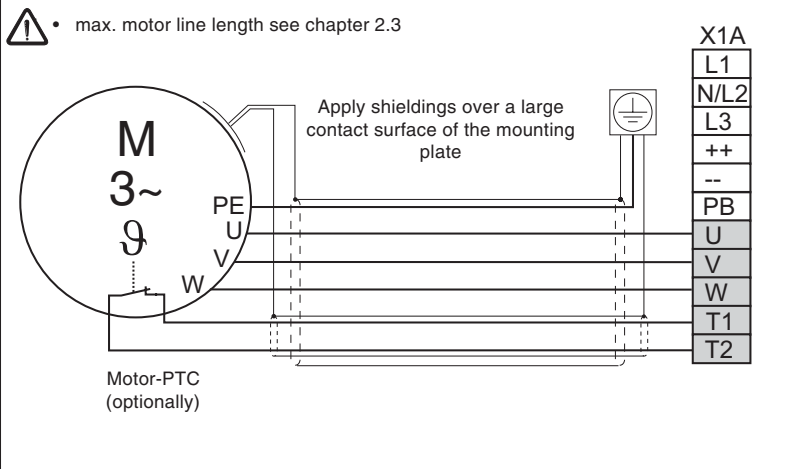
*Some countries demand that the PE-terminal is directly connected to the terminal box (not over the mounting plate).*

## 3.3.3 Mains connection

<p><i>Mains connection 230 V 1-phase</i></p> <p>1 x 180...260 V AC</p>	<p><i>Mains connection 230 V 3-phase</i></p> <p>3 x 180...260 V AC</p>
<p>Protection</p> <ul style="list-style-type: none"> <li>• Fuse (see chapter 2.3) or</li> <li>• Power protective switch</li> <li>• 1-phase inverter RCD Type A or Type B</li> <li>• 3-phase inverter RCMA with separator or RCD Type B</li> </ul>	<p><i>Mains connection 400 V 3-phase</i></p> <p>3 x 305...500 V AC</p>
<p><i>DC-connection 230 V-class</i></p> <p>250...370 V DC</p>	<p><i>DC-connection 400 V-class</i></p> <p>420...720 V DC</p>

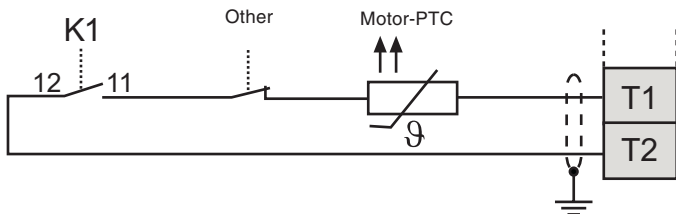
# Installation and Connection

## 3.3.4 Motor connection



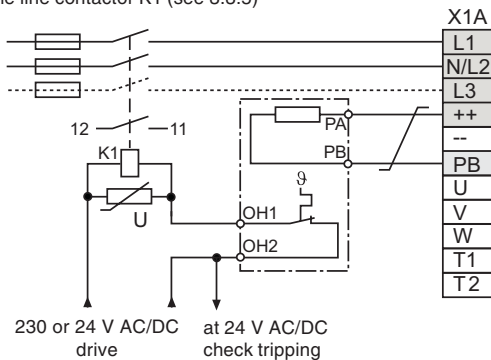
## 3.3.5 External temperature monitoring

- Terminals T1, T2
- Tripping resistance 1.65...4 kOhm
- Reset resistance 0.75...1.65 kOhm
- Design in accordance with VDE 0660 Part 302
- This function can be activated by the machine builder by software
- Do not lay connecting cable together with control cable
- Permissible in the motor cable only with double shielding
- Connect relay K1 for fire prevention in regenerative operation (see 3.3.6)



## 3.3.6 Connection of the braking resistor with temperature monitoring

- PA, PB Connector for braking resistor (see chapter 2.2)
- Technical data (see chapter 2.3)
- During clearing of the temperature monitoring the input voltage is switched off
- for additional protection in regenerative operation connect the auxiliary contacts 11 and 12 of the line contactor K1 (see 3.3.5)



Braking resistors can develop very high surface temperatures, therefore install as safe-to-touch as possible.

# Installation and Connection

## 3.4 Control Board Basic

### 3.4.1 X2A Control Terminal Strip

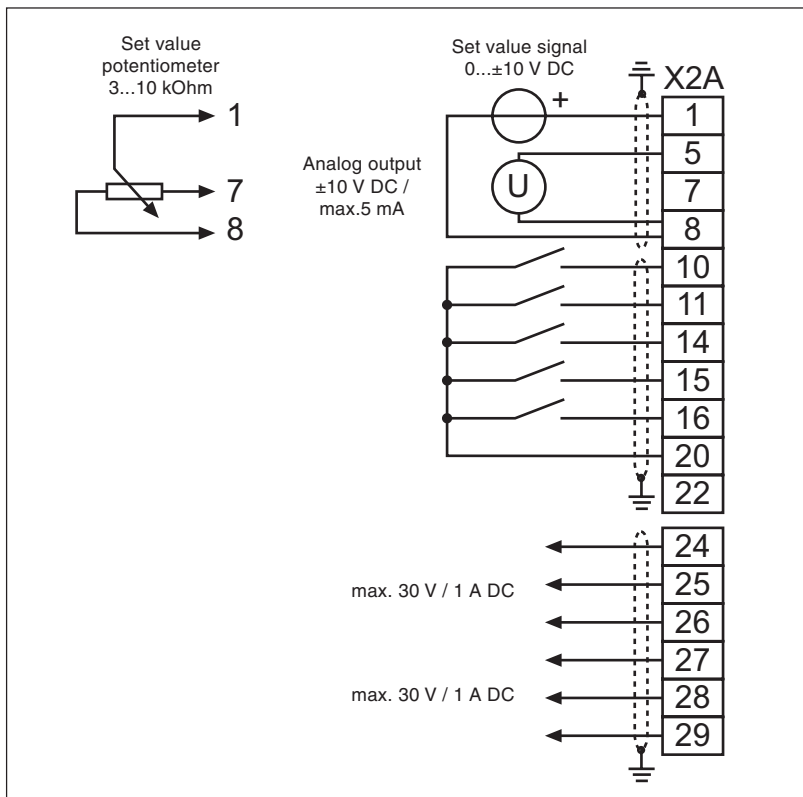
- Tightening torque 0,22...0,25 Nm (2 lb inches)
- Use shielded/drilled cables
- Lay shield on one side of the inverter onto earth potential

X2A



PIN	Function	Name	Description
1	+ Set value input	AN1+	Differential voltage inputs 0...±10 VDC; Ri = 55kOhm
2	- Set value input	AN1-	AN1: Setting of the analog set value
5	Progr. analog outputs		0...±10 VDC / max. 5 mA; defined by the manufacturer
7	Analog output 1	AO1	Output of the actual output frequency 0...±100 Hz
8	+ 10 V Output	CRF	Reference voltage for set value poti (max. 4 mA)
10	Analog Mass	COM	Mass for analog in- and outputs
11	Prog. Digital inputs		Function of the inputs is defined by the manufacturer
14	Fixed frequency 1 (CP.19)	I1	13...30 VDC ±0% smoothed; Ri: 2,1 kOhm; scan time 1 ms
15	Fixed frequency 2 (CP.20)	I2	I1 + I2 = Fixed frequency 3 (CP.21)
16	Forward	F	Preset rotation;
17	Reverse	R	Forward has priority
18	Control release/ Reset	ST	Power modules are enabled; reset at opening
20	24 V-Output	U <sub>out</sub>	Supply of the programmable inputs
22	Digital Mass	0V	Potential for digital in- /outputs
24	Relay 1 / NO contact	RLA	Programmable relay output (CP.31)
25	Relay 1 / NC contact	RLB	Load ability max. 30 VDC / 1A
26	Relay 1 / switching contact	RLC	Factory setting: Fault relay
27	Relay 2 / NO contact	FLA	Programmable relay output (CP.32)
28	Relay 2 / NC contact	FLB	Load ability max. 30 VDC / 1A
29	Relay 2 / switching contact	FLC	Factory setting: Frequency dependent switch

## 3.4.2 Connection of the control terminal strip



To avoid interferences a separate shielding must be provided for analog and digital control lines. Depending on the use of the relay outputs, an extra shielding is to be used, too.

In case of inductive load on the relay outputs a protective wiring must be provided (e.g. free-wheeling diode)!

# Installation and Connection

## 3.5 Control Board General

### 3.5.1 X2A Control Terminal Strip

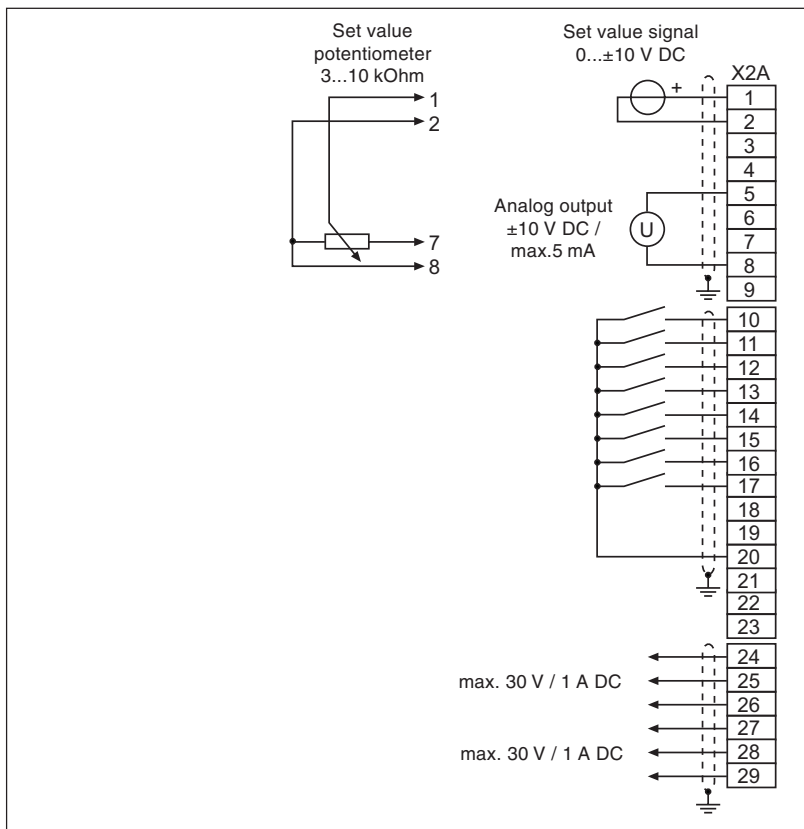


- Tightening torque 0,22...0,25 Nm (2 lb inches)
- Use shielded/drilled cables
- Lay shield on one side of the inverter onto earth potential

PIN	Function	Name	Description
1	+ Set value input	AN1+	Differential voltage inputs 0...±10 VDC; Ri = 55kOhm
2	- Set value input	AN1-	AN1: Setting of the analog set value
3	+ Analog input	AN2+	AN2: no function at KEB factory settings
4	- Analog input	AN2-	
5	Progr. analog outputs		0...±10 VDC / max. 5 mA; defined by the manufacturer
6	Analog output 1	AO1	Output of the actual output frequency 0...±100 Hz
7	Analog output 2	AO2	Output of the apparent current 0...2 x I <sub>N</sub>
8	+ 10 V Output	CRF	Reference voltage for set value poti (max. 4 mA)
9	Analog Mass	COM	Mass for analog in- and outputs
10	Analog Mass	COM	Mass for analog in- and outputs
11	Prog. Digital inputs		Function of the inputs is defined by the manufacturer
12	Fixed frequency 1 (CP.19)	I1	13...30 VDC ±0% smoothed; Ri: 2,1 kOhm; scan time 1 ms
13	Fixed frequency 2 (CP.20)	I2	I1 + I2 = Fixed frequency 3 (CP.21)
14	External fault	I3	Input for external fault setting (E.EF)
15	DC-braking	I4	Activates the DC-braking (CP.22/23)
16	Forward	F	Preset rotation;
17	Reverse	R	Forward has priority
18	Control release/ Reset	ST	Power modules are enabled; reset at opening
19	Reset	RST	Reset; only when an error occurs
20	Digital outputs		max. 50 mA; function is defined by the manufacturer
21	Transistor output 1	O1	switched at factual = fset
22	Transistor output 2	O2	Ready signal (switched as long as no error occurs)
23	24 V-Output	U <sub>out</sub>	Supply of the programmable inputs
24	20...30 V-Input	U <sub>in</sub>	Voltage input for external supply
25	Digital Mass	0V	Potential for digital in- /outputs
26	Digital Mass	0V	Potential for digital in- /outputs
27	Relay 1 / NO contact	RLA	Programmable relay output (CP.31)
28	Relay 1 / NC contact	RLB	Load ability max. 30 VDC / 1A
29	Relay 1 / switching contact	RLC	Factory setting: Fault relay
30	Relay 2 / NO contact	FLA	Programmable relay output (CP.32)
31	Relay 2 / NC contact	FLB	Load ability max. 30 VDC / 1A
32	Relay 2 / switching contact	FLC	Factory setting: Frequency dependent switch



## 3.5.2 Connection of the control terminal strip



To avoid interferences a separate shielding must be provided for analog and digital control lines. Depending on the use of the relay outputs, an extra shielding is to be used, too.



In case of inductive load on the relay outputs a protective wiring must be provided (e.g. free-wheeling diode)!

# Operation of the Unit

## 4 Operation of the Unit

### 4.1 Operation Accessories

#### 4.1.1 With HSP5 cable and without operator

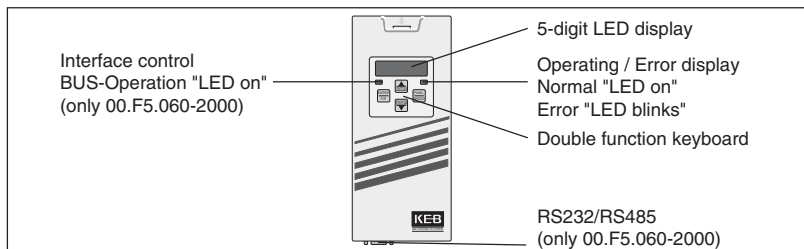
A special cable (Part no. 00.F5.0C0-0001) is necessary for the control of the KEB COMBIVERT without operator. It is connected between the HSP5-interface X4A and a serial RS232-PC-interface (COM1 or COM2). The operation takes place via the PC-program COMBIVIS.



The HSP5-cable has an integrated level converter. The connection of a serial standard cable would destroy the PC-interface.

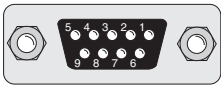
#### 4.1.2 Digital operator (Part no.: 00.F5.060-1000)

As an accessory for the local operation of the KEB COMBIVERT F5 an operator is available. To prevent malfunctions, the inverter must be brought into **nOP** status before connecting / disconnecting the operator (open control release terminal). When starting the inverter, it is always started with the last stored values or the factory setting.

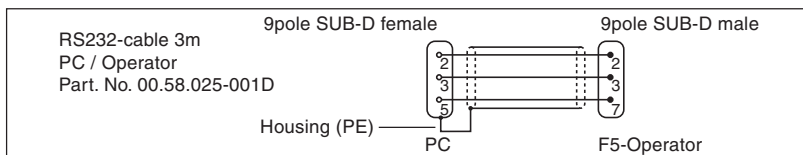


#### 4.1.3 Interface operator (Part No.: 00.F5.060-2000)

The interface operator corresponds to the functional range of the digital operator. However, it is enhanced by a serial RS232/485-interface.

		PIN	RS485	Signal	Meaning
1	—	—	—	—	reserved
2	—	—	—	TxD	Transmitter signal/RS232
3	—	—	—	RxD	Receiver signal/RS232
4	A'	—	—	RxD-A	Receiver signal A/RS485
5	B'	—	—	RxD-B	Receiver signal B/RS485
6	—	—	—	VP	Voltage supply - Plus +5V ( $I_{\max} = 10 \text{ mA}$ )
7	C/C'	—	—	DGND	Data reference potential
8	A	—	—	TxD-A	Transmitter signal A/RS485
9	B	—	—	TxD-B	Transmitter signal B/RS485

A RS232-cable is needed to connect the interface operator with the PC. The assignment is represented on the following page.



## 4.1.4 Remote control (HSP5-extension)

The HSP5-extension is connected between the COMBIVERT and the operator. It serves for the remote control of the COMBIVERT. The HSP5-extension is equipped with special cable drivers. Therefore the use of conventional RS232-cables is not permitted. The last three digits of the part number indicate the length of the cable in dm (00.F5.0C0-1005, -1010, -1030 und 1100).

## 4.1.5 Other operators

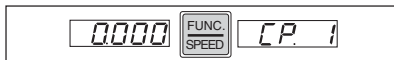
In addition to the described operators the KEB COMBIVERT can be equipped with further operators for special applications (Profibus, Interbus, Sercos, CAN, DeviceNet). You find further information on that on our home page.

## 4.2 Keyboard Operation

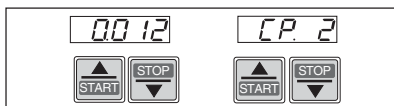
### 4.2.1 Parameter numbers and values

When switching on KEB COMBIVERT F5 the value of parameter CP.1 appears.

The **function key** (FUNC) changes between the parameter value and parameter number.

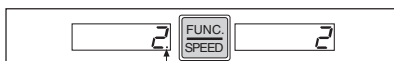


With **UP** (▲) and **DOWN** (▼) the value of the parameter number is increased/decreased with **changeable** parameters.



Principally during a change, parameter values are immediately accepted and stored non-volatile. However, with some parameters it is not useful that the adjusted value is accepted immediately. In these cases the adjusted value is accepted and stored non-volatile by pressing **ENTER**. When this type of parameter is changed a point appears behind the last digit.

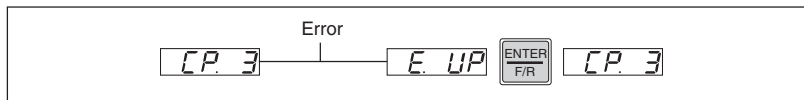
By pressing „ENTER“ the adjusted value is accepted and non-volatile stored.



## Operation of the Unit

### 4.2.2 Resetting error messages

If a malfunction occurs during operation, the actual display is overwritten by the alarm message. The alarm message in the display is reset by ENTER.



With ENTER only the error message in the display is reset. In order to reset the error itself, the cause must be removed or a power-on reset must be made.

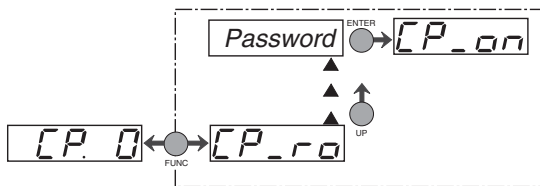
### 4.2.3 Password input

The KEB COMBIVERT is outfitted with a comprehensive password protection. In dependence on the entered password the following modes are possible.

Display	Mode
CP_ro	End customer menu (CP-Parameter) read-only
CP_on	End customer menu (CP-Parameter) read/write
CP_SE	Service menu (like end customer menu, but with the original parameters )
APPL	Application menu (all parameter groups and parameters are visible)
ohne	Drive mode (COMBIVERT can be put into operation by the keyboard )

The menu admissible for the application is defined by the machine builder. The password input is generally made over the parameter CP.0. The adjusted password/menu is maintained even after switching off.

*Example: Changing the CP-parameter from read-only to read/write*



## 5. Parameter description

Dis-play	Parameter	Setting range	Reso-lution	De-fault	Unit	En-ter	Origin
CP.0	password input	0...9999	1	-	-	-	ud.1
CP.1	actual frequency display	-400...400	0,0125	0	Hz	-	ru.3
CP.2	set frequency display	-400...400	0,0125	0	Hz	-	ru.1
CP.3	inverter status display	0...255	1	0	-	-	ru.0
CP.4	apparent current	0...6553,5	0,1	0	A	-	ru.15
CP.5	apparent current/peak value	0...6553,5	0,1	0	A	-	ru.16
CP.6	utilization	0...65535	1	0	%	-	ru.13
CP.7	intermediate circuit voltage	0...1000	1	0	V	-	ru.18
CP.8	interm. circuit vol./peak value	0...1000	1	0	V	-	ru.19
CP.9	output voltage	0...778	1	0	V	-	ru.20
CP.10	minimal frequency	0...400	0,0125	0	Hz	-	op.6
CP.11	maximal frequency	0...400	0,0125	0	Hz	-	op.10
CP.12	acceleration time	0,00...300,00	0,01	5	s	-	op.28
CP.13	deceleration time (-1=CP.12)	-0,01...300,00	0,01	5	s	-	op.30
CP.14	s-curve time	0,00...5,00	0,01	0	s	-	op.32
CP.15	boost	0,0...25,5	0,1	2	%	-	uf.1
CP.16	rated frequency	0...400	0,0125	50	Hz	-	uf.0
CP.17	voltage stabilization	1...650 (off)	1	0	V	E	uf.9
CP.18	switching frequency	0...LTK	1	LTK	-	E	uf.11
CP.19	fixed frequency 1	-400...400	0,0125	5	Hz	-	op.21
CP.20	fixed frequency 2	-400...400	0,0125	50	Hz	-	op.22
CP.21	fixed frequency 3	-400...400	0,0125	70	Hz	-	op.23
CP.22	DC braking / mode	0...9	1	7	-	E	pn.28
CP.23	DC braking / time	0,00...100,00	0,01	10	s	-	pn.30
CP.24	max. ramp current	0...200	1	140	%	-	pn.24
CP.25	max. constant current	0...200	1	200:off	%	-	pn.20
CP.26	speed search condition	0...15	1	8	-	E	pn.26
CP.27	quick stop time	0,00...300,00	0,01	2	s	-	pn.60
CP.28	reaction of ext. overtemperat.	0...7	1	7	-	-	pn.12
CP.29	analog output 1 / function	0...20	1	2	-	E	an.31
CP.30	analog output 1 / amplification	-20,00...20,00	0,01	1	-	-	an.33
CP.31	relay output 1 / function	0...70	1	4	-	E	do.2
CP.32	relay output 2 / function	0...70	1	27	-	E	do.3
CP.33	relay output 2 / switching level	±30000,00	0,01	4	-	-	le.3
CP.34	source of rotation direction	0...9	1	2	-	E	op.1
CP.35	AN1 set value selection	0...2	1	0	-	E	an.0
CP.36	AN1 zero hysteresis	-10,0...10,0	0,1	0,2	%	-	an.4

### CP.3 Inverter status

In parameter „inverter status“ the actual operating condition of the frequency inverter is displayed. In the case of an error the current error message is displayed, even if the display has already been reset with ENTER (error-LED on the operator is still blinking).

nOP „no Operation“ control release not bridged, modulation switched off, output voltage = 0 V, drive is not controlled.

LS „Low Speed“ no rotation preset, modulation switched off, output voltage = 0 V, drive is not controlled.

FAcc „Forward Acceleration“ drive accelerates with direction of rotation forward .

FdEc „Forward Deceleration“ drive decelerates with direction of rotation forward.

rAcc „Reverse Acceleration“ drive accelerates with direction of rotation reverse.

rdEc „Reverse Deceleration“ drive decelerates with direction of rotation reverse.

Fcon „Forward Constant“ drive runs with a constant speed and direction of rotation forward.

rcon „Reverse Constant“ drive runs with constant speed and direction of rotation reverse.

You find information on status messages as well as on the cause and removal of error messages under [www.keb.de](http://www.keb.de) ==> *Documentation* ==> *Operating Instructions* ==> *Other* ==> *Service informations* ==> *Error and status messages.doc*.

### CP.17 Voltage stabilization

With this parameter a regulated output voltage in relation to the rated frequency can be adjusted. For that reason voltage variations at the input as well as in the intermediate circuit only have a small influence on the output voltage (U/f-characteristic). The function allows, among other things, an adaption of the output voltage to special motors.

## CP.22 DC-braking / Mode

With DC-braking the motor is not decelerated by the ramp. Quick braking is caused by D.C. voltage, which is applied onto the motor winding. This parameter determines how the dc-braking is triggered.

Value	Activation
0	DC-braking deactivated
1	DC-braking at switch off of the direction of rotation and upon reaching 0Hz. The braking time is CP.23 or until the next direction of rotation.
2*	DC-braking as soon as setting for the direction of rotation is absent.
3*	DC-braking as soon as the direction of rotation changes or is absent.
4*	DC-braking on disabling the direction of rotation and if the real frequency falls below 4 Hz.
5*	DC-braking when the real frequency falls below 4 Hz and the drive decelerates
6*	DC-braking as soon as the set value falls below 4 Hz.
7*	DC-braking when input I4 is switched. At control circuit B = value „0“.
8	DC-braking as long as input I4 is switched. At control circuit B = value „0“.
9	DC-braking after switching on the modulation on.

\* Braking time depends on the actual frequency.

## CP.24 Max. ramp current

This function protects the frequency inverter against switching off through overcurrent during the acceleration ramp. When the ramp reaches the adjusted value, it is stopped so long until the current decreases again. CP.3 displays "LAS" at active function.

## CP.25 Max. constant current

This function protects the frequency inverter against switch off through overcurrent during constant output frequency. When exceeding the adjusted value, the output frequency is reduced until the value drops below the adjusted value. CP. 3 displays "SSL" at active function.

## CP.26 Speed search condition

When connecting the frequency inverter onto a decelerating motor, an error can be triggered by the differing rotating field frequencies. With activated speed search the inverter searches for the actual motor speed, adapts its output frequency and accelerates with the adjusted ramp to the given set value. During speed search CP.3 displays „SSF“. The parameter determines, under what conditions the functions operate. In case of several conditions the sum of the value must be entered. Example: CP.26 = 12 means after reset **and** after auto-reset UP.

Value	Condition
0	function off
1	at control release
2	at switch on
4	after reset
8	after Auto-Reset UP

## CP.28 Reaction of external overtemperature

This parameter determines the response of the drive on the external temperature monitoring (**factory setting = off**). In order to activate this function the power circuit terminals T1/T2 must be connected in accordance with the instruction manual Part 2. After that the response can be adjusted according to following table. If overheat no longer exists, the message E.ndOH (or A.ndOH) is output. Only then the error can be reset or the automatic restart can be carried out.

CP.28	Display	Reaction	Restart
0	<b>E.dOH</b>	Immediate disabling of modulation	Remove fault;
1*	<b>A.dOH</b>	Quick stopp. / disabling of modul. after reaching speed 0	Actuate
2*	<b>A.dOH</b>	Quick stopping/holding torque at speed 0	reset
3	<b>A.dOH</b>	Immediate disabling of modulation	autom. reset,
4*	<b>A.dOH</b>	Quick stopp. / disabling of modul. after reaching speed 0	if fault is no
5*	<b>A.dOH</b>	Quick stopping/holding torque at speed 0	longer present
6*	<b>keine</b>	No effect on the drive; With CP.31/32 = 9 an external module can be controlled (e. g. fan)	- inapplicable -
7	<b>keine</b>	No effect on the drive; <b>!No malfunction!</b> External Temperature monitoring is not activated.	

\*) If the motor is still too hot after 10 seconds, the error E.dOH is triggered and the modulation is switched off!

## CP.29 Analog output 1 / Function

CP.32 defines the function of analog output 1.

Value	Function	Standardization 0...100 % ( $\pm 100$ %)
0	absolute actual frequency CP.3	0...100 Hz
1	absolute set frequency CP.2	0...100 Hz
2	actual frequency CP.3	0... $\pm 100$ Hz
3	set frequency CP.2	0... $\pm 100$ Hz
4	output voltage CP.9	0...500 V
5	DC voltage CP.7	0...1000 V
6	apparent current CP.4	0...2 • Irated
7	active current ru.17	0...2 • $\pm$ Irated
8-10	application mode only	
11	absolute active current ru.17	0...2 • Irated
12	power mod. temperature ru.38	0...100 °C
13	motor temperature ru.46	0...100 °C
14-18	application mode only	
19	ramp output frequency ru.2	0... $\pm 100$ Hz
20	absolute ramp output frequency ru.2	0...100 Hz



## CP.31 Relay output 1 / Function (X2A.24...26)

## CP.32 Relay output 2 / Function (X2A.27...29)

The switching level of CP.31 is 100,00. The switching level of CP.32 is CP.33!

Value	Function
0	No function (generally off)
1	Generally on
2	Run signal; also by DC-braking
3	Ready signal (no error)
4	Fault relay
5	Fault relay (no auto-reset)
6	Warning or error message at abnormal stopping
7	Overload alert signal
8	Overttemperature alert signal power modules
9	External Overttemperature alert signal motor
11	Overttemperature alert signal interior OHI
12	Cable breakage 4...20 mA on analog input 1
14	Max. constant current (stall, CP.25) exceeded
15	Max. ramp current (LA-Stop CP.24) exceeded
16	DC-braking active
20	Actual value=set value (CP.3=Fcon, rcon; not at noP, LS error,SSF)
21	Accelerate (CP.3 = FAcc, rAcc, LAS)
22	Decelerate (CP.3 = FdEc, rdEc, LdS)
23	Real direction of rotation = set direction of rotation
24	Utilization (CP.6) > 100%
25	Active current > switching level
26	Intermediate circuit voltage (CP.7)>switching level
27	Real value (CP.1) > switching level
28	Set value (CP.2) > switching level
31	Absolut set value on AN1 > switching level
32	Absolut set value on AN2 > switching level
34	Set value on AN1 > switching level
35	Set value on AN2 > switching level
40	Hardware current limit activated
41	Modulation on
44	Inverter status (CP.3) = switching level
45	Power module temperatur > Level
46	Motor temperatur > Level
47	Ramp output frequency > Level
48	Apparent current (CP.4) > Level
49	Clockwise rotation (not at noP, LS, abnormal stopping, Fehler)
50	Counter clockwise (not at noP, LS, abnormal stopping, Fehler)
63	Absolut ANOUT1 > switching level
64	Absolut ANOUT2 > switching level
65	ANOUT1 > switching level
66	ANOUT2 > switching level
70	Driver voltage active (safety-relay)

Values 10, 13, 17-19, 29, 30, 33, 36-39, 42, 43, 51-62, 67-69 only application-mode

### CP.34 Source of rotation direction

The source rotation setting and the mode of evaluating the rotation setting is defined with this parameter (Enter-Parameter). With CP.34 one does not modify the rotation source of the fixed frequencies (CP.19... 21).

Value	Function
0/1	Only application mode
2	Setting by way of terminal strip forward/reverse; negative set values are set to zero (factory setting)
3	Setting by way of terminal strip forward/reverse; the signs of the setpoint values have no effect on the direction of rotation
4	Setting by way of terminal strip run/stop (X2A.14) and forward/reverse (X2A.15); negative values are set to zero
5	Setting by way of terminal strip run/stop (X2A.14) and forward/reverse; the signs of the setpoint values have no effect on the direction of rotation
6	Set value dependent, positive value - clockwise rotation; negative value counterclockwise rotation; with set value „0“ it is switched into status „Low speed“ (LS)
7	Set value dependent, positive value - clockwise rotation; clockwise rotation is indicated
8/9	Only application mode

### CP.35 AN1 Set value selection

The set value input 1 (AN1) at the F5-GENERAL control can be triggered by various signal levels. In order to correctly evaluate the signal, this parameter must be adapted to the signal source. At the F5-BASIC control the signal source may not be re-adjusted.

Value	Reference signal
0	0...±10 V DC / Ri = 56 kOhm
1	0...+20 mA DC / Ri = 250 Ohm
2	4...20 mA DC / Ri = 250 Ohm

## 6. Certifications

### 6.1 CE-Marking

CE marked frequency inverter and servo drives were developed and manufactured to comply with the regulations of the Low-Voltage Directive 73/23/EEC.

The inverter / servo drive must not be started until it is determined that the installation complies with 89/392/EEC (machine directive) as well as the EMC-directive (89/336/EEC)(note EN60204).

The frequency inverters / servo drives meet the requirements of the Low-Voltage Directive 73/231/EEC. The harmonized standards of the series EN 50178 in connection with EN 60439-1 and EN 60146 were used.

This is a product of limited availability in accordance with IEC 61800-3. This product may cause radio interference in residential areas. In this case the operator may need to take corresponding measures.

### 6.2 Manufacturer's Declaration

A manufacturer declaration in accordance with 89/392/EEC can be provided by KEB if needed.

### 6.3 UL / CUL - Marking



**To be conform according to UL and CUL for the use on the North American Market the following instructions must be observed:**

- Inverter is suitable for use on a circuit capable of delivering not more than 10 kA rms (symmetrical), 240 V AC or 480 V AC maximum
- maximum surrounding air temperature 45°C (113 °F)
- Motor protection by adjustment of current parameters
- not incorporated with overspeed protection
- Power terminal tightening torque (see type plate)
- Control terminal tightening torque (see chapter 3.4)
- Overload protection at 130 % of inverter output rated current (see type plate)
- Refer to this installation instructions for proper wiring

### 7. Additional Manuals

You find supplementary manuals and instructions for the download under

**[www.keb.de](http://www.keb.de) > Documentation > Operation instruction**

General instructions

- Part 1 EMC-and safety instructions

Unit-specific instructions

- Part 2 Power Circuit
- Part 3 Control Circuit

Service notes

- Up- /Download of parameter lists with KEB COMBIVERT
- Error messages

Instruction and information for construction and development

- Application Manual
- Preparation of a user-defined parameter menu
- Programming of the digital inputs

All documents are also available in printed version, however we have to charge a nominal fee for these.





**Karl E. Brinkmann GmbH**

Försterweg 36 - 38 • D - 32683 Barntrup  
Telefon 00 49 / 52 63 / 4 01 - 0 • Fax 00 49 / 52 63 / 4 01 - 1 16  
Internet: www.keb.de • E-mail: info@keb.de

**KEB Antriebstechnik GmbH & Co. KG**

Wildbacher Str. 5 • D - 08289 Schneeberg  
Telefon 0049 / 37 72 / 67 - 0 • Telefax 0049 / 37 72 / 67 - 2 81  
E-mail: info@keb-combidrive.de

**KEB Antriebstechnik Austria GmbH**

Ritzstraße 8 • A - 4614 Marchtrenk  
Tel.: 0043 / 7243 / 53586 - 0 • FAX: 0043 / 7243 / 53586 - 21  
Kostelní 32/1226 • CZ - 370 04 České Budějovice  
Tel.: 00420 / 38 / 731 92 23 • FAX: 00420 / 38 / 733 06 97  
E-mail: info@keb.at

**KEB Antriebstechnik**

Herenveld 2 • B - 9500 Geraardsbergen  
Tel.: 0032 / 5443 / 7860 • FAX: 0032 / 5443 / 7898  
E-mail: koen.detaeye@keb.de

**KEB China**

Xianxia Road 299 • CHN - 200051 Shanghai  
Tel.: 0086 / 21 / 62350922 • FAX: 0086 / 21 / 62350015  
Internet: www.keb-cn.com • E-mail: info@keb-cn.com

**Société Française KEB**

Z.I. de la Croix St. Nicolas • 14, rue Gustave Eiffel  
F - 94510 LA QUEUE EN BRIE  
Tél.: 0033 / 1 / 49620101 • FAX: 0033 / 1 / 45767495  
E-mail: sfkeb.4@wanadoo.fr

**KEB (UK) Ltd.**

6 Chieftain Business Park, Morris Close  
Park Farm, Wellingborough, GB - Northants, NN8 6 XF  
Tel.: 0044 / 1933 / 402220 • FAX: 0044 / 1933 / 400724  
Internet: www.keb-uk.co.uk • E-mail: info@keb-uk.co.uk

**KEB Italia S.r.l.**

Via Newton, 2 • I - 20019 Settimo Milanese (Milano)  
Tel.: 0039 / 02 / 33500782 • FAX: 0039 / 02 / 33500790  
Internet: www.keb.it • E-mail: kebitalia@keb.it

**KEB - YAMAKYU Ltd.**

711 Fukudayama, Fukuda  
J - Shinjo-Shi, Yamagata 996 - 0053  
Tel.: 0081 / 233 / 29 / 2800 • FAX: 0081 / 233 / 29 / 2802  
E-mail: kebjs001@d4.dion.ne.jp

**KEB Portugal**

Lugar de Salgueiros - Pavilhão A, Mouquim  
P - 4760 V. N. de Famalicão  
Tel.: 00351 / 252 / 371 318 • FAX: 00351 / 252 / 371 320  
E-mail: keb.portugal@netc.pt

**KEB Taiwan Ltd.**

1F, No.19-5, Shi Chou Rd., Tounan Town  
R.O.C. - Yin-Lin Hsian / Taiwan  
Tel.: 00886 / 5 / 5964242 • FAX: 00886 / 5 / 5964240  
E-mail: keb\_taiwan@mail.apol.com.tw

**KEBCO Inc.**

1335 Mendota Heights Road  
USA - Mendota Heights, MN 55120  
Tel.: 001 / 651 / 4546162 • FAX: 001 / 651 / 4546198  
Internet: www.kebco.com • E-mail: info@kebco.com