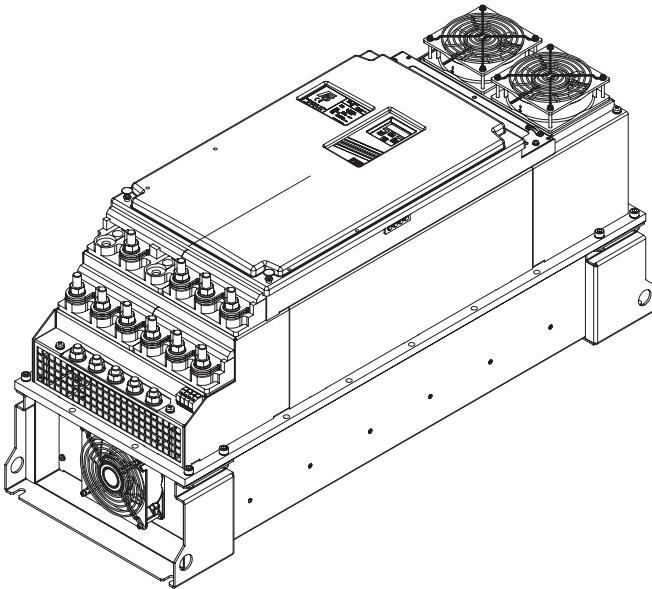


# ERGÄNZUNG

## S U P P L E M E N T



**200...630 kW**



**Leistungsteil**



**Power Circuit**

**Gehäuse P**

**Housing P**

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## 1. General

This supplement describes the frequency inverter KEB COMBIVERT F5 in a P-housing in the power range of 200...630 kW.

Sizes 28 and 29 are used as single components. Further sizes are achieved with the combination of two or more single components. The control is made here only with one unit. This manual is only valid together with the instruction manual COMBIVERT F5 (Part 2). Both instruction manuals must be made available to the user. Prior to performing any work on the unit the user must familiarize himself with the unit. This includes especially the knowledge and observance of the safety and warning directions of Part 1. The pictographs used in this instruction manual have following meaning:



Danger  
Warning  
Caution



Attention,  
observe at  
all costs



Information  
Help  
Tip

# Technical Data

## 2. Technical Data

Inverter Size	28	29	32	33	34	35	36	-	-
Housing Size	P								
Phases	3	3	2 x 3	2 x 3	2 x 3	3 x 3	3 x 3	-	-
Output nominal power [kVA]	256	319	492	554	616	692	796	-	-
Max. rated motor power [kW]	200	250	400	450	500	560	630	-	-
Output nominal current [A]	370	460	710	800	890	1000	1150	-	-
Max. short time current <sup>1)</sup> [A]	462	575	887	1000	1112	1500	1725	-	-
OC-tripping current [A]	554	690	1065	1200	1335	1800	2070	-	-
Nominal input current [A]	385	483	746	840	935	1050	1208	-	-
Rated operating frequency [kHz]	2	2	2	2	2	2	2	-	-
Max. operating frequency [kHz]	4	4	4	4	4	4	4	-	-
Power loss at nominal operating [W]	3500	4200	6800	7600	8500	9500	10700	-	-
Max. permissible mains fuse (inert) [A]	550	700	2x550	2x700	2x700	-	-	-	-
Line cross section <sup>2)</sup> [mm <sup>2</sup> ]	2x95	2x150	-	-	-	-	-	-	-
Min. braking resistor <sup>3)</sup> [Ohm]	2,4			2 x 2,4		3 x 2,4		-	-
Typ. braking resistor <sup>3)</sup> [Ohm]	-	-	-	-	-	-	-	-	-
Max. braking current [A]	330			2 x 330		3 x 330		-	-
Tightening torque for terminals [Nm]						-			
Mains voltage (rated voltage) <sup>4)</sup> [V]				305...500 ±0 (400 V)					
Mains frequency [Hz]					50 / 60 +/- 2				
Output voltage [V]					3 x 0...U <sub>N</sub>				
Output frequency [Hz]					0...1600				
Shielded motor line length [m]					100				
Max. heat sink temperature TOH [°C]					90				
Storage temperature [°C]					-25...70				
Operating temperature <sup>5)</sup> [°C]					-10...45				
Model / protective system					IP20				
EMC tested in accordance with ...				EN 61800-3					
Climatic category (EN 60721-3-3)				3K3					
Pollution degree (IEC 664-1)				2					
Vibration/Jolt				-					
Weight [kg]				300					

1) With the regulated systems F5-M as well as F5-S 5% are to be subtracted as control reserve.

2) Recommended minimum cross section of the motor wire for rated power and a cable length of upto 100m (copper)

3) This data is only valid for units with internal brake transistor GTR 7 (see "unit identification")

4) At rated voltage ≥ 460V multiply the output rated current with factor 0,86

5) The output frequency should not exceed 1/10 of the switching frequency.

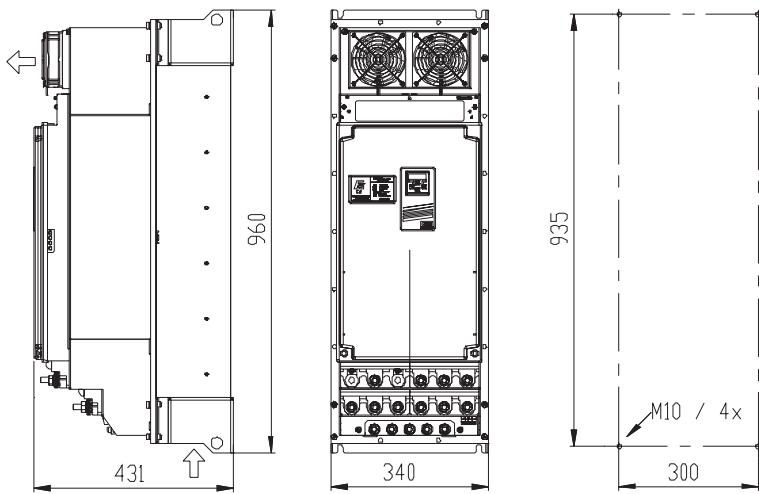
6) The temperature range is only valid for the power and control circuit. The temperature range for the power circuit is dependent on the control cabinet installation and the cooling system.

**i** The technical data is for 2/4-pole standard motors. With other pole numbers the inverter must be dimensioned onto the motor rated current. Contact KEB for special or medium frequency motors.

Site altitude max. 2000 m. With site altitudes over 1000 m a power reduction of 1% per 100 m must be taken into consideration.

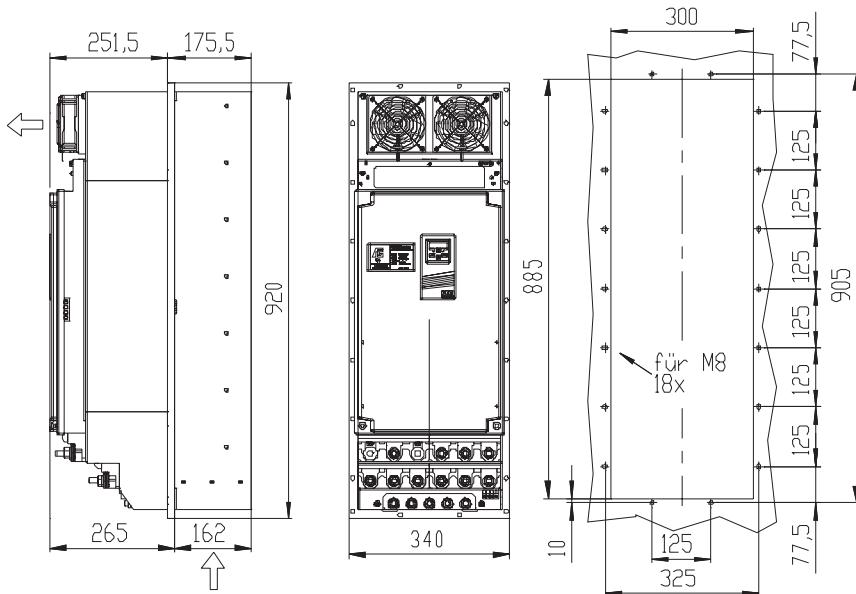
## 2.3 Dimensions

### 2.3.1 Standard Version



### 2.3.2 Through-Mount Version

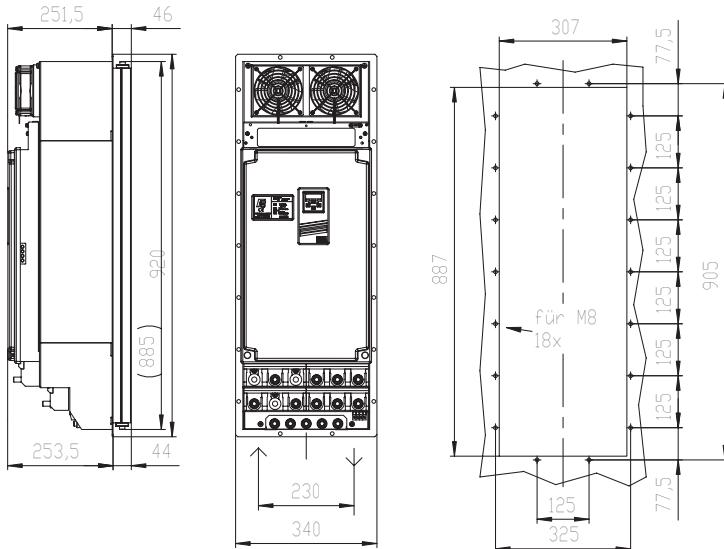
At this design the heat sink is moved through a section of the control cabinet to the outside.



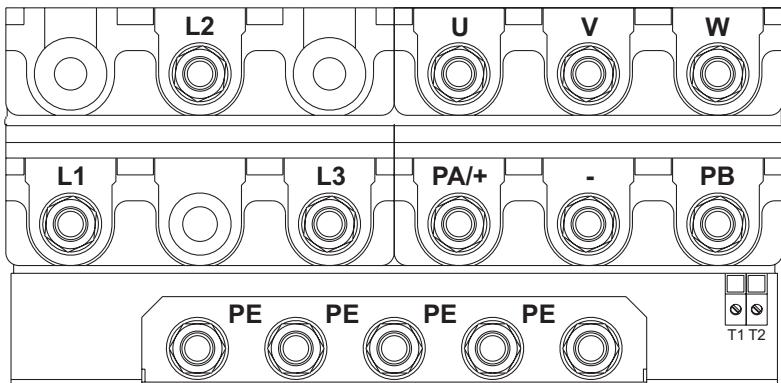
# Power Circuit Terminals

## 2.3.3 Water-Cooling

This design is laid out to integrate COMBIVERT to an existing cooling system. At this design the instructions in the instruction manual 00.F5.01W-Kxxx for water-cooled units must be observed.



## 2.4 Summary of the Power Circuit Connections



- |                   |  |
|-------------------|--|
| <b>L1, L2, L3</b> | 3-phase mains connection                                 |
| <b>U, V, W</b>    | Motor connection   |
| <b>PA+, PB</b>    | Connection for braking resistor                          |
| <b>PA+, -</b>     | Connection for feedback unit<br>(DC link voltage output) |
| <b>T1, T2</b>     | Connection for temperature sensor                        |
| <b>PE</b>         | Connection for shielding / earthing                      |

## 2.5 Connection Accessories

### 2.5.1 Component Sets

Size	Phases	Figure	Component set	Filter	Line shoke
28	3	1	28.U5.A1W-3000	1 x 28.E4.T60-1001	1 x 28.DR.B28-8031
29	3	1	29.U5.A1W-3000	1 x 30.E4.T60-1001	1 x 29.DR.B28-5331
32	3	2	32.U5.A1W-3000	1 x 32.E4.T60-1001	2 x 28.DR.B28-8031
33	3	3	33.U5.A1W-3000	2 x 28.E4.T60-1001	2 x 28.DR.B28-8031
34	3	3	34.U5.A1W-3000	2 x 30.E4.T60-1001	2 x 29.DR.B28-8031
35	3	4	35.U5.A1W-3000	3 x 28.E4.T60-1001	3 x 28.DR.B28-8031
36	3	4	36.U5.A1W-3000	3 x 28.E4.T60-1001	3 x 28.DR.B28-8031

### 2.5.2 Filter

Filter	U <sub>max</sub>	Nominal current	Leakage current	Motor line	Weight
28.E4.T60-1001	3 x 500 V	410 A	60 mA	30 m	18,1 kg
30.E4.T60-1001	3 x 500 V	800 A	60 mA	30 m	20,6 kg
32.E4.T60-1001	3 x 500 V	1000 A	60 mA	30 m	25 kg

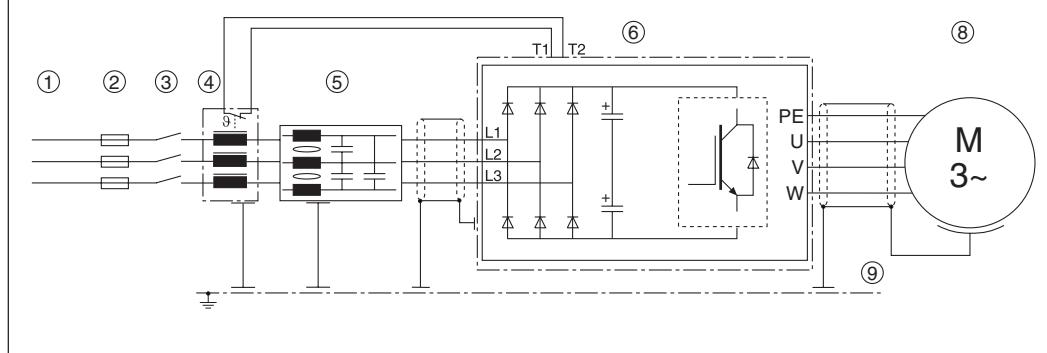
### 2.5.3 Chokes

Line choke	Input	Nominal current	U <sub>k</sub>	Inductance	Weight
28.DR.B28-8031	3 ph / 400 V	400 A	4%	0,081 mH	61 kg
29.DR.B28-5331	3 ph / 400 V	580 A	4%	0,051 mH	73,5 kg

## 2.6 Connection of the Power Circuit

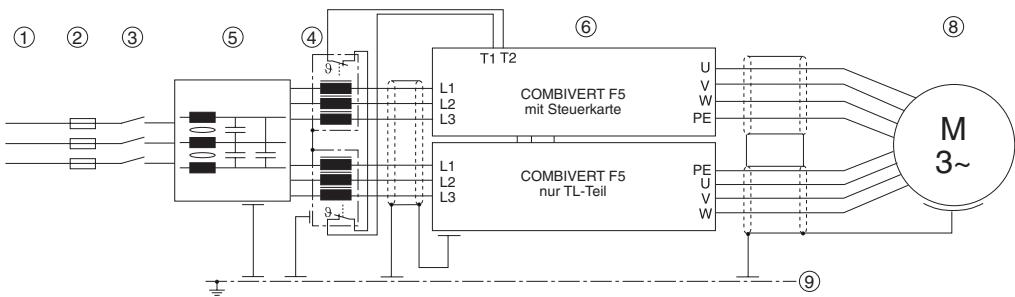
 Exchanging the mains and motor connection leads to immediate destruction of the unit. Pay attention to the supply voltage and the correct direction of rotation of the motor !

Connection diagram 1

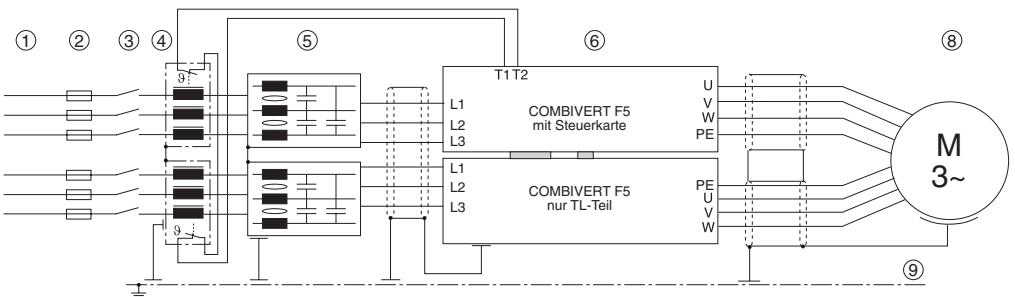


# Connection of the power unit

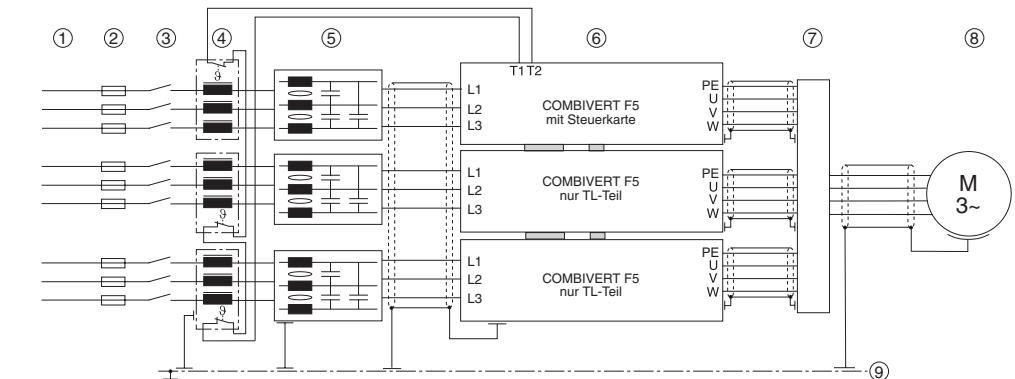
Connection diagram 2



Connection diagram 3

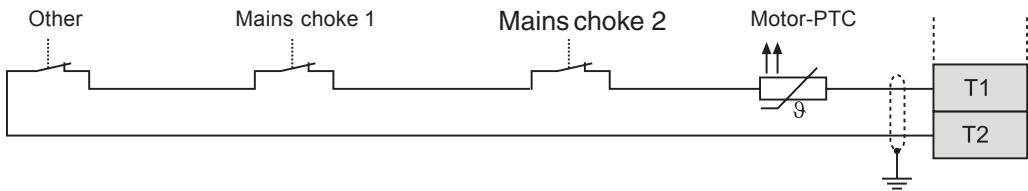


Connection diagram 4



1	Supply line	6	KEB COMBIVERT
2	Main fuse	7	Terminal block
3	Main contactor	8	Motor
4	Mains choke with temperature detection	9	Mounting plate
5	HF-Filter		

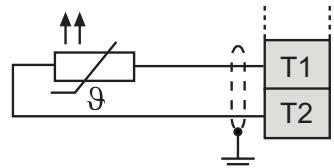
## 2.7 Temperature sensing series connection



**⚠** During connection the temperature sensors of the input chokes are to be switched in series, since otherwise these are destroyed in the case of an error by overheating. The connection is always made at the master inverter.

**⚠** KTY- or PT100 sensor may not be integrated in the temperature sensing series connection, otherwise the contact of the main contactor or other switching units will be simmered!

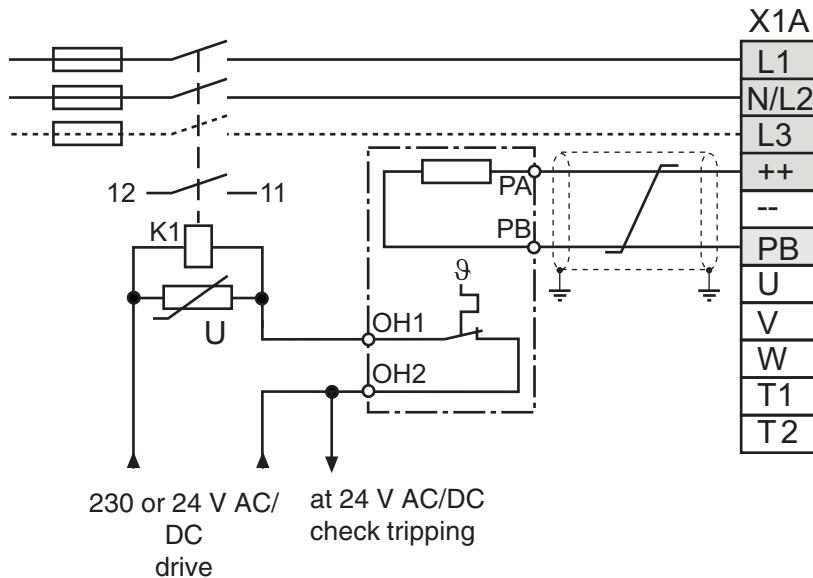
KTY/ PT100



In order to detect the overheating of a braking resistor it is absolutely necessary to monitor the temperature switch of the braking resistor. The overheating can have following causes:

- ramps too short or the operation-time too long
- incorrect dimension of the braking resistor
- input voltage too high
- defect of braking transistor in the inverter or the braking module

The connection of the mains voltage offers the only protection in the case of a defective braking transistor (see diagram).



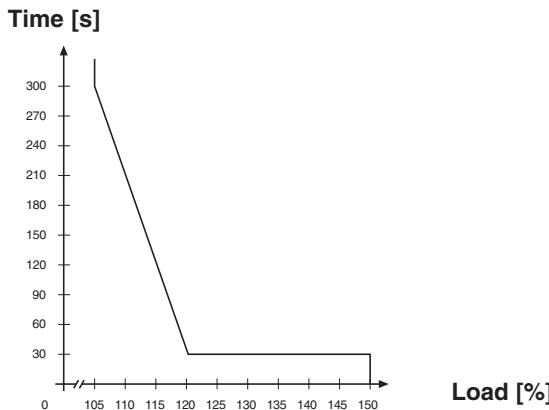
During clearing of the temperature monitoring the input voltage is switched off. For additional protection in regenerative operation connect the auxiliary contacts 11 and 12 of the line contactor K1 into the temperature series connection.

A simplified protection is achieved, if the links of the temperature sensor are integrated into the temperature detection in accordance with following drawing. This measure does not protect with a defect of the braking transistor however against the developing extreme load with acute danger of fire.

So that an evaluation occurs at F5-B/G, this must be activated with the software of the control card (CP.28 / see control circuit).

### 3. Annex

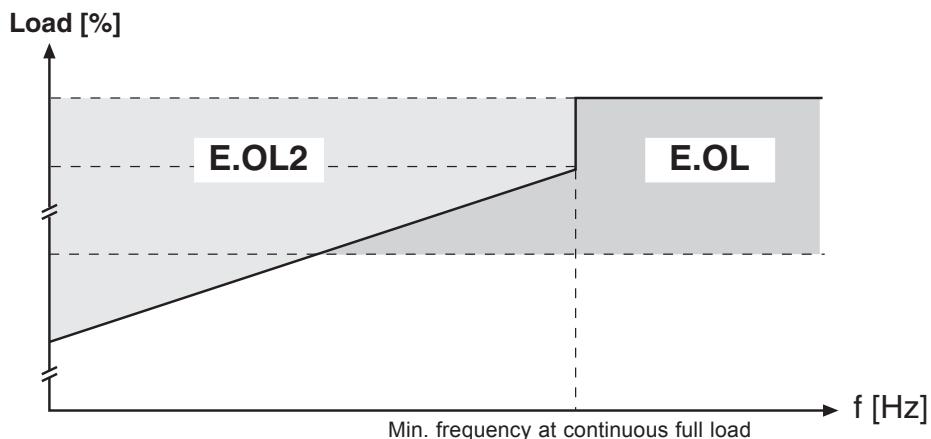
#### 3.1 Overload Characteristics



On exceeding a load of 105% the overload integrator starts. When falling below the integrator counts backwards. If the integrator achieves the overload characteristic that corresponds to the inverter, the error E.OL is triggered.

#### 3.2 Overload Protection in the lower Speed Range

(only valid for F5-M and F5-S, stall current see technical data)





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